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practical tools you can
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Eq.(2.5.5) can be
written in the form.

$m\ddot{y}(t)+c\dot{y}(t)+k y(t)$
 $=p(t)$ (2.5.6) This has
the same form as the
equation for a simple

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SDOF system. m , c , k
 $p(t)$ are called
the generalized mass,
generalized damping
coefficient,
generalized stiffness
and.

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Shashank updated on
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11:43am IST

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stiffness of the one
story frame with an
intermediate realistic
stiffness of the beam.

The system has 3
DOFs as shown.

Assume $L = 2h$ and EI
 $b = EI c$. ANS:-

Question 2: ...

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does most of the work for you, as opposed to manually having to animate super complex motion like cloth blowing in the wind.

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