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Brady. This book, by a  
leading authority on  
legged locomotion,  
presents exciting  
engineering and science,  
along with fascinating  
implications for theories  
of human motor control.

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That fundamental  
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locomotion, one of the  
least developed areas of  
robotics, addressing the  
possibility of building  
useful legged robots that  
run and balance. The  
book describes the study  
of physical machines  
that run and balance on  
just one leg, including  
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Balance" is fifteenth in  
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Intelligence Series,  
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legged locomotion,  
presents exciting  
engineering and science,  
along with fascinating  
implications for theories



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of human motor control.

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The team engineered the robot as simply a torso and two legs, and designed the system specifically to test lower-body tasks, such as locomotion and balance.

As with its full-body

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counterpart, Little  
HERMES is designed  
for teleoperation, with  
an operator suited up in  
a vest to control the  
robot's actions.

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mimics human balance  
while running and ...  
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Author: ... Van Ham R  
and Lefeber D (2006)

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walking robot actuated  
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artificial muscles ...

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organized as a textbook,  
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That Balance, presents exciting engineering and science, along with fascinating implications for theories of human motor control. It lays fundamental groundwork in legged locomotion, one of the least developed areas of robotics, addressing the possibility of building useful legged robots that run and balance.

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Locomotion over different terrain types, whether flat or uneven, is very important for a wide range of service operations in robotics. Potential applications range from surveillance, rescue, or hospital assistance. Wheeled-legged hexapod robots have been designed to

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solve these locomotion tasks. Given the wide range of feasible operations, one of the key operation planning issues is related to ...

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Featherstone<sup>3</sup>, Darwin  
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Semini<sup>1</sup> Abstract The  
ability of legged  
systems to traverse  
highly-constrained  
environments depends  
by and large on the per-  
formance of their  
motion and balance  
controllers. This paper

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